



AI4Science – LANL’s ArtIMis Investment

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HPC-DESIGN
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ML Lead for Enabling Manufacturing

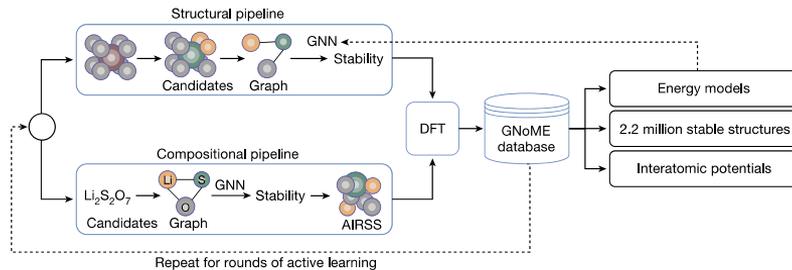
February, 2026

LA-UR-26-21430

Industry has led the way on AI for science but is unlikely to lead a sustained effort.

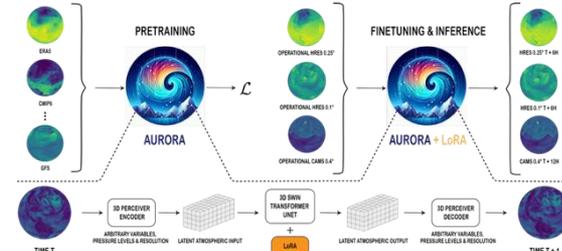
- Need institutions with long horizons, open verification, and mission alignment
- Commercial incentives favor demo cycles, product pivots, and PR wins
- DeepMind's materials project walked back after analysis by LBNL
- Meta's Galactica taken offline days after release
- IBM sold off Watson Health – market alignment diverged from scientific utility

Materials at DeepMind



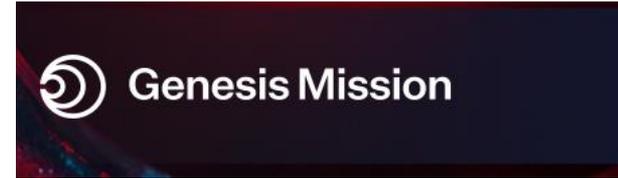
Less successful than initial claims.

Earth Systems at Microsoft



Effort abandoned.

DOE has invested significant effort to develop an AI strategy.



Secretary Wright visited LANL to discuss Manhattan Project 2.0.

https://www.youtube.com/watch?v=Gyr_wOSy_xQ

Application Areas



Our goal is to develop an ecosystem of **agents** and **foundation models** to address **DOE mission needs**.

Enabling Technologies



Application Areas



Emily discussed this yesterday

Enabling Technologies



Moved to lab-wide effort

We have built over a dozen special purpose science foundation models including . . .

Stochastic Latent Transformers and VAEs



LATTE

GPT-like (discrete tokens)



UNet-based

Shape-agnostic PDE Foundation Model
<https://huggingface.co/mahindrautela/MORPH>



Transformer-based



Most models are:

- Trained on autoregressive roll-outs
- Multi-modal (input decks, equations, simulation data)
- Fine-tuned on new datasets (across domain)
- Fine-tuned for specific scalar outputs (time to fracture, physics numeric quantity, etc.)

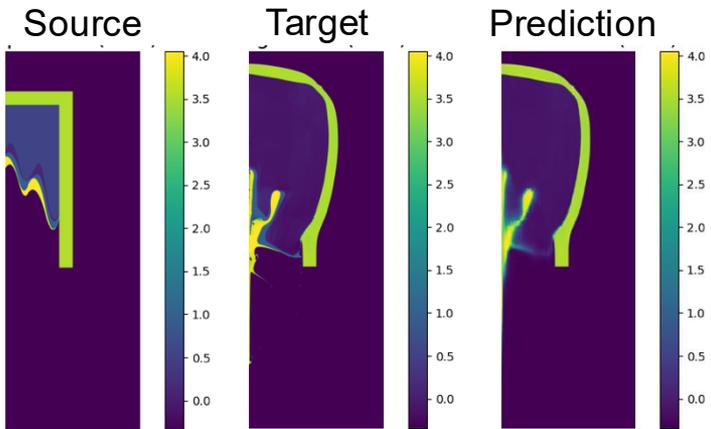
True foundation models – not just surrogate models



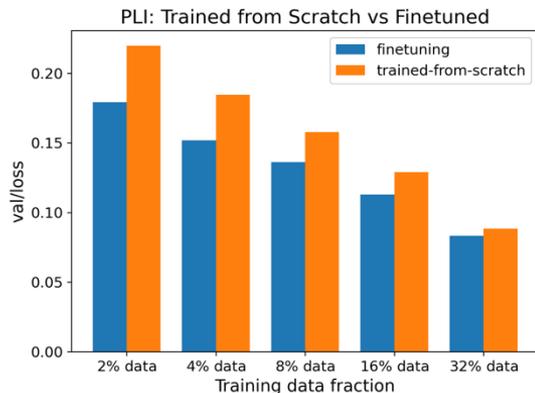
FindingPhysics

Looking for a good name still ☺

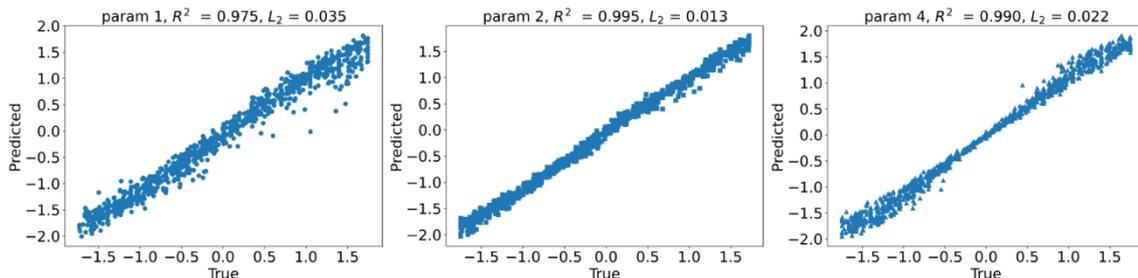
Results on PLI dataset (MPMM)



Pretraining advantage



Results on JAG-ICF dataset (LLNL)

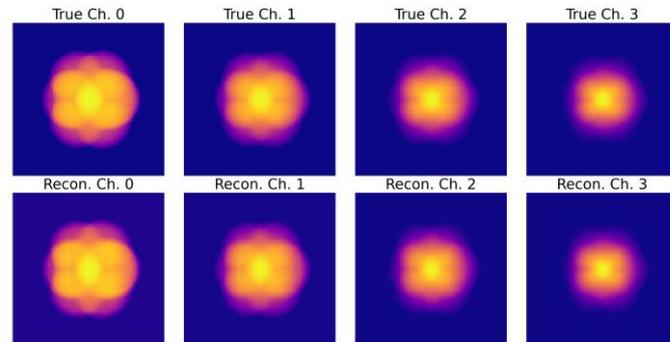


Parameter estimation

- $R^2 = 0.995$
- $MSE = 0.0235$

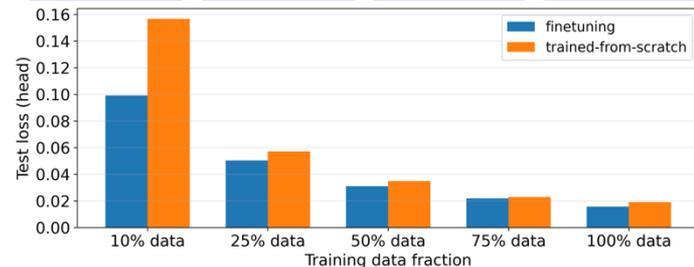
Recons MSE:

- 0.0012

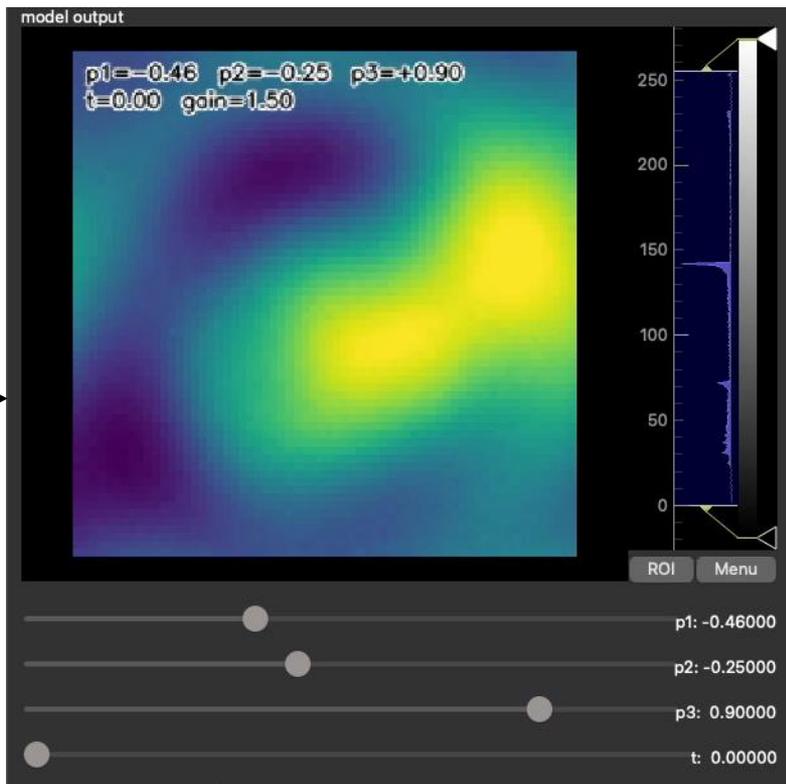


Pretraining advantage

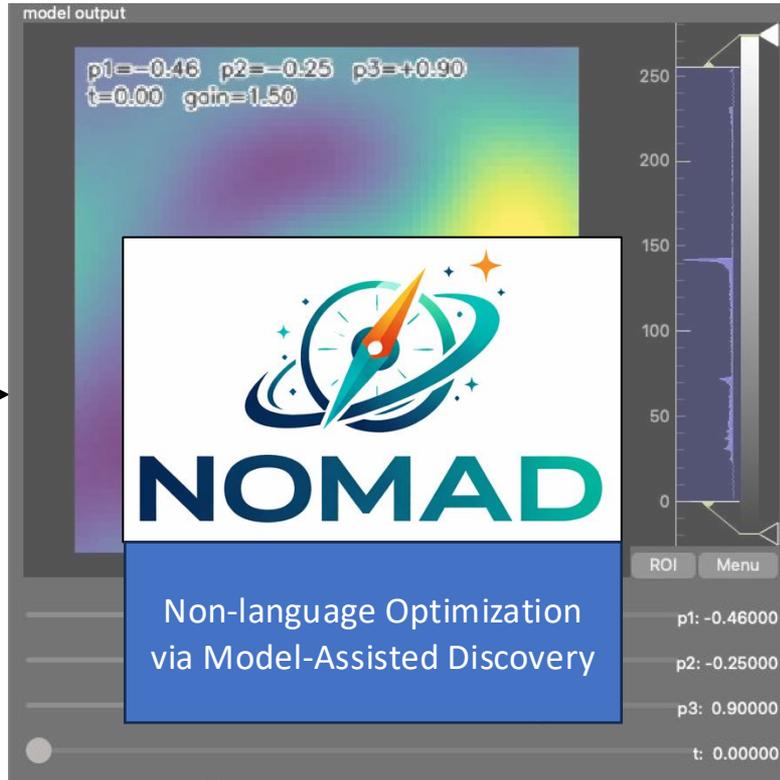
- 60% for 10% data.
- Reduces later



LANL Staff Can Use Surrogate Models to Explore Designs



But we can also drive those FMs with reasoning agents



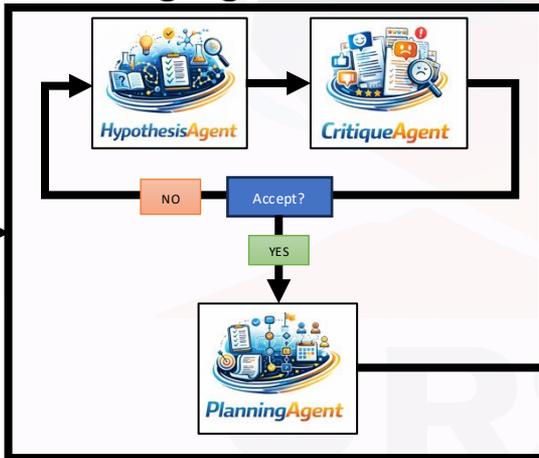
We are building an agentic design and discovery system driven by industry reasoning models.

Inputs



“Find a new alloy that resists fracture at low temperatures. Test it in a desired configuration and maximize time to failure.”

Thinking Agents



Task Agents





“Find a ligand that could become a cancer drug.”

Hypothesis Generation

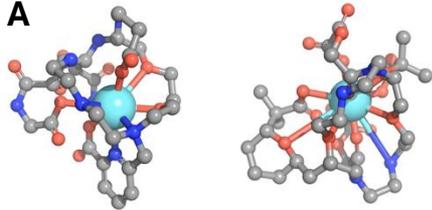


Nemotron-Super-49B

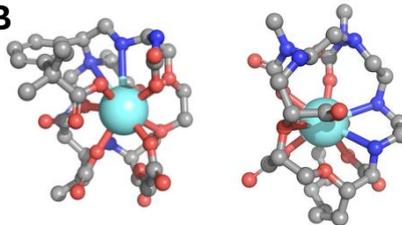
Hypothesis Evaluation



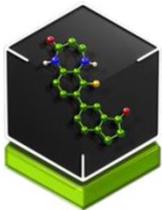
Group A



Group B



Molecule Design



GenMol

Complex Construction

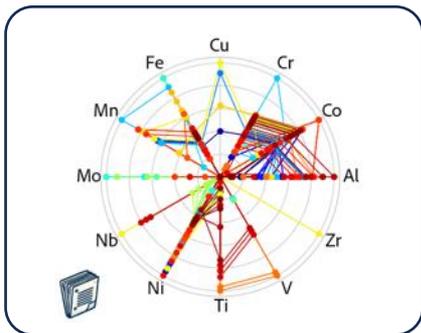


Computational Modeling

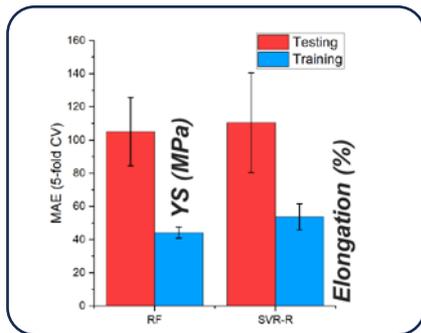
$$\hat{H}\Psi = E\Psi$$



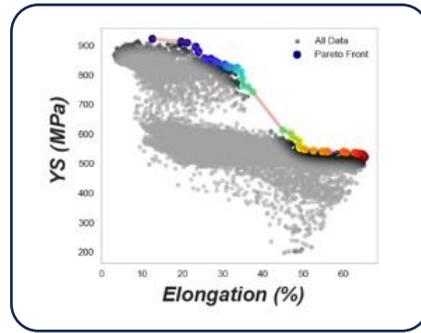
We are automating a materials design lab for alloy discovery.



Data collection from literature. Automated.



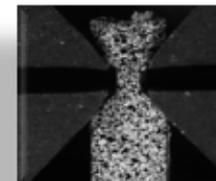
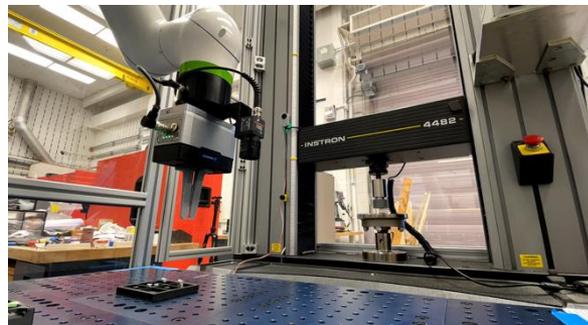
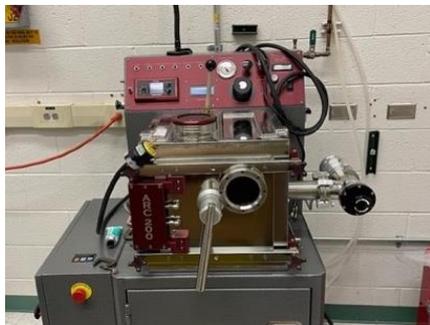
Property prediction. Partially automated



Model Inversion. Partially automated.



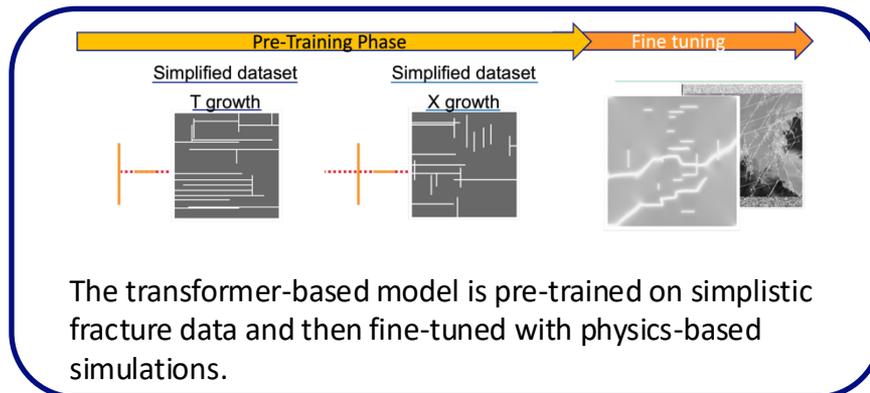
Manufacturing and testing. Partially automated.



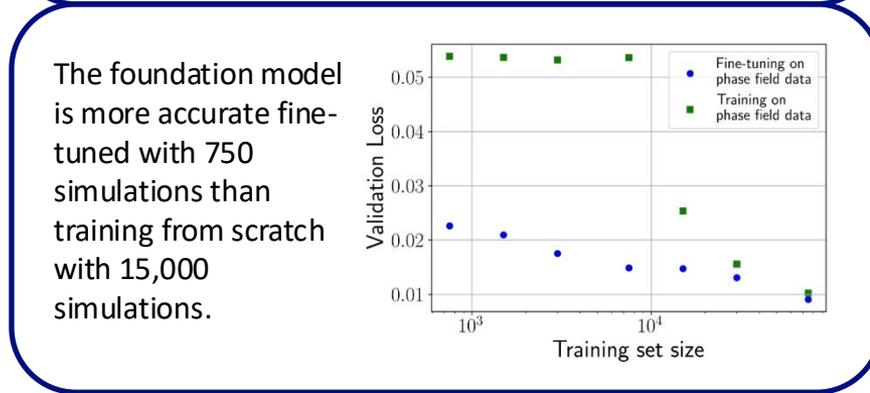
Team Leads: Saryu Fensin and Tim Germann



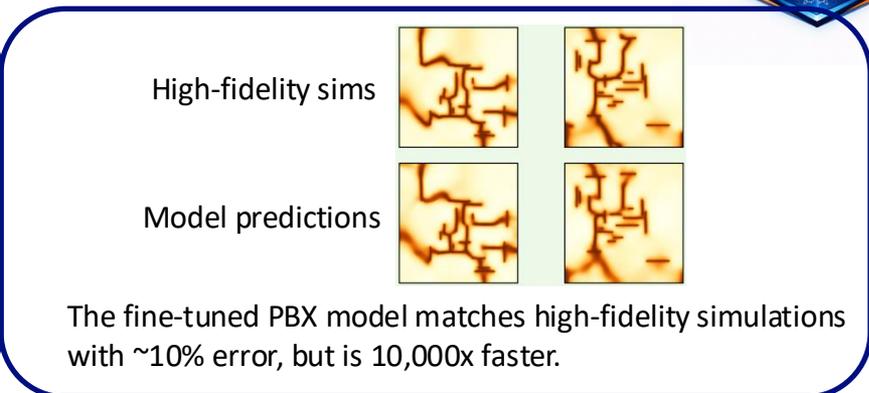
The fracture foundation model predicts PBX fractures that match physics sims, but 10,000x times faster.



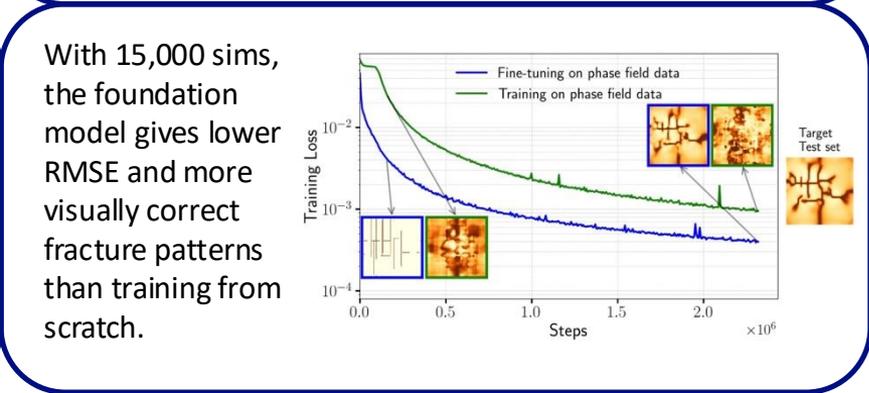
The transformer-based model is pre-trained on simplistic fracture data and then fine-tuned with physics-based simulations.



The foundation model is more accurate fine-tuned with 750 simulations than training from scratch with 15,000 simulations.



The fine-tuned PBX model matches high-fidelity simulations with ~10% error, but is 10,000x faster.



With 15,000 sims, the foundation model gives lower RMSE and more visually correct fracture patterns than training from scratch.

Models include tuning we have found useful

- Curriculum learning – tasks get progressively harder
- Scheduled sampling – sample from either ground truth or rollout during training
- “Pushforward trick”
- Data augmentation (including noise injection)
- Domain-relevant loss functions
- And more

MESSAGE PASSING NEURAL PDE SOLVERS

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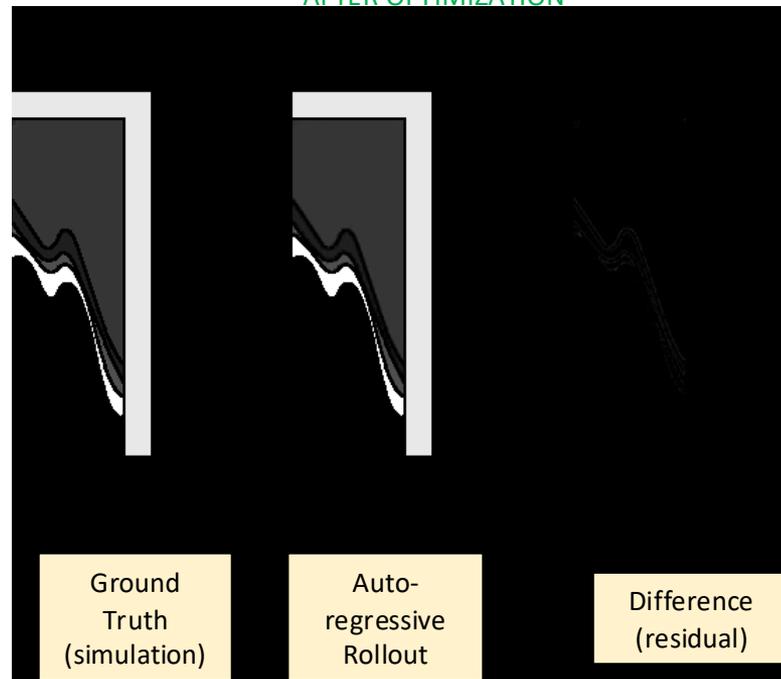
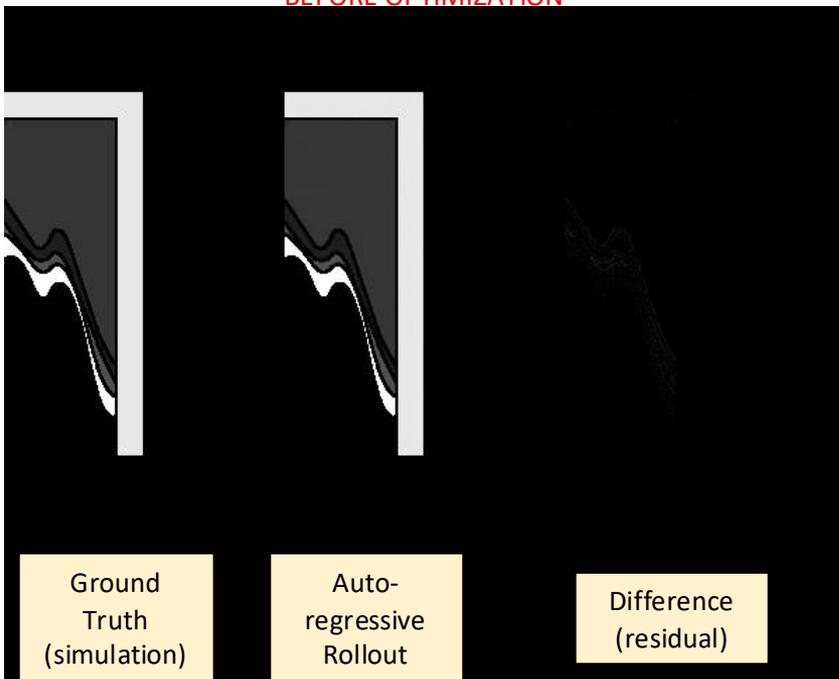
Max Welling
University of Amsterdam
m.welling@uva.nl

We have invested heavily in improving auto-regressive rollouts



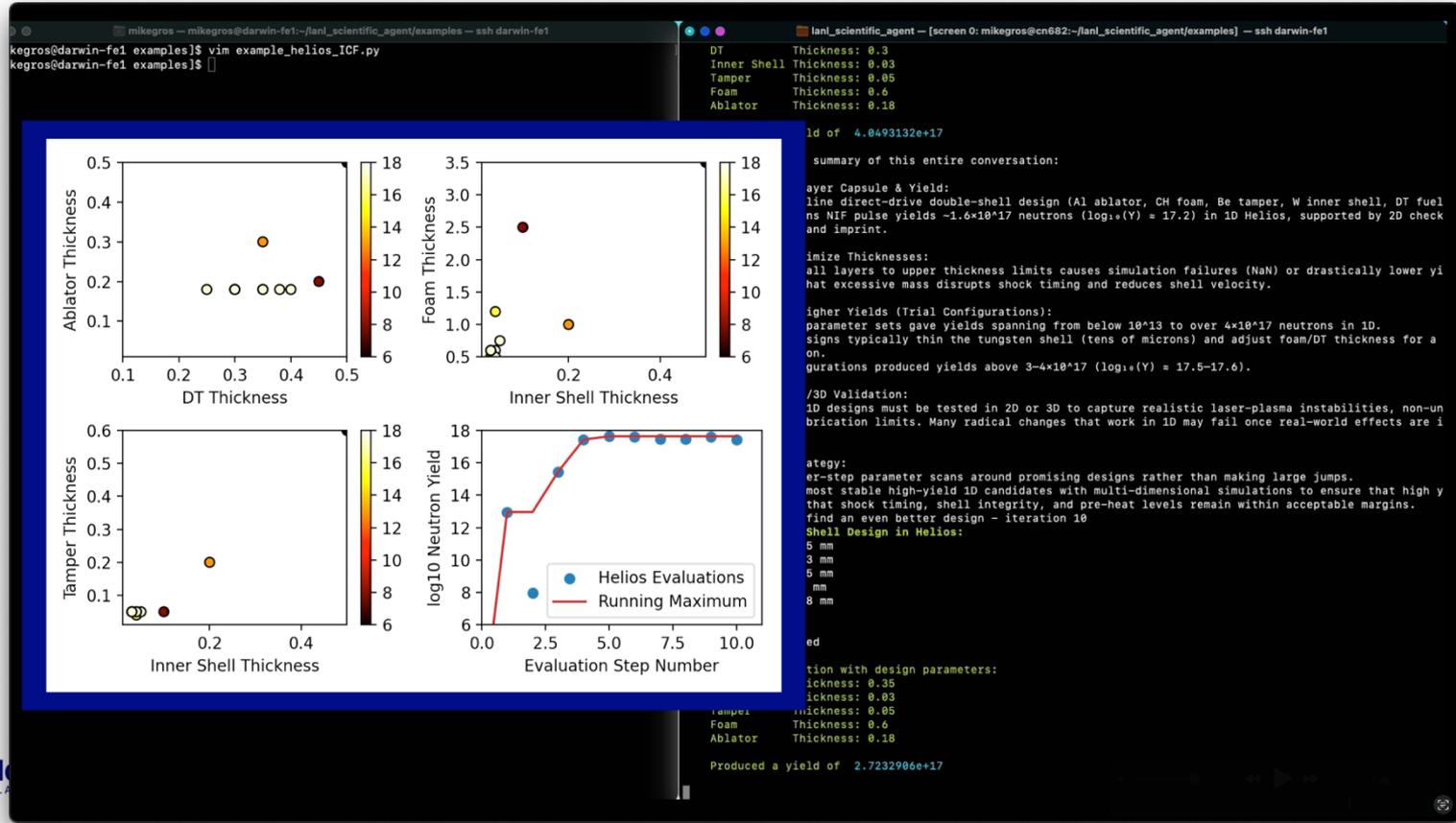
BEFORE OPTIMIZATION

AFTER OPTIMIZATION



HEAT dataset: LA-UR-25-26490
<https://oceans11.lanl.gov/>

We have an ICF design demo combining planning, research, simulation, and data processing agents.



The planning agent does a careful breakdown with expected outputs and success criteria.

```
Plan
[
  {
    "id": "step_0",
    "name": "Set-up & Folder Structure",
    "description": "Create/confirm a working directory that contains (i) this step-plan, (ii) a sub-folder \"code\" for all Python scripts, (iii) a sub-folder \"data\" for every CSV produced, and (iv) a sub-folder \"figures\" for every saved plot.",
    "requires_code": false,
    "expected_outputs": [
      "Working directory exists",
      "Sub-folders: code/, data/, figures/"
    ],
    "success_criteria": [
      "All required folders exist",
      "Folders are write-able"
    ]
  },
  {
    "id": "step_1",
    "name": "Generate ≥ 100 Candidate Energetic SMILES",
    "description": "Programmatically or manually compile a list of at least 100 syntactically valid SMILES strings biased toward energetic motifs (e.g., nitro, nitrate ester, azide, nitramine, N-oxide). Store them one per line in data/candidate_smiles.txt.",
    "requires_code": false,
    "expected_outputs": [
      "data/candidate_smiles.txt (≥ 100 lines)"
    ],
    "success_criteria": [
      "File exists and contains ≥ 100 non-empty lines",
      "Each line passes RDKit MolFromSmiles validation"
    ]
  },
  {
    "id": "step_2",
    "name": "Write Batch-Evaluator",
    "description": "Create step_2_1_run_model.py that reads candidate_smiles.txt, calls './bin_for_demo/MIST_FOR_URSA.sh <SMILES>' via subprocess, parses vdet/pdet/density, writes data/raw_results.csv (smiles_vdet, pdet, density, status), retries failed calls ≤ 3 times and logs persistent failures.",
    "requires_code": true,
    "expected_outputs": [
      "code/step_2_1_run_model.py",
      "data/raw_results.csv"
    ],
    "success_criteria": [
      "Script runs without uncaught exceptions",
      "raw_results.csv has ≥ 100 rows with status == OK"
    ]
  }
]
```

```
mist_agent_macho-orafish
Name
├── _pycache__
├── checkpoint.db
├── outputs
│   ├── candidate_smiles_raw.txt
│   ├── predictor_path.txt
│   ├── seed.txt
│   ├── step_2_1_smiles_lib.csv
│   ├── step_2_1_raw_results.csv
│   ├── step_4_1_clean_log.txt
│   ├── step_4_1_clean_results.csv
│   ├── step_5_1_pareto_results.csv
│   ├── step_5_1_with_pareto.csv
│   ├── step_5_2_pareto_only.csv
│   ├── step_6_1_all.png
│   ├── step_6_2_pareto.png
│   ├── step_6_3_pairgrid.png
│   ├── step_7_1_summary.md
│   ├── valid_smiles_smoketest.txt
│   ├── step_0_1_create_output_dir.py
│   ├── step_0_2_set_seeds.py
│   ├── step_0_3_write_seed.py
│   ├── step_0_4_print_bootstrap_ok.py
│   ├── step_1_1_resolve_executable_path.py
│   ├── step_1_2_run_cmd_wrapper.py
│   ├── step_1_3_predict_props.py
│   ├── step_1_4_self_test_predict_props.py
│   ├── step_2_1_enumerate_scaffolds.py
│   ├── step_2_2_combinatorial_generation.py
│   ├── step_2_3_predictor_smoke_test.py
│   ├── step_2_4_write_csv.py
│   ├── step_3_1_load_input_library.py
│   ├── step_3_2_predict_and_accumulate.py
│   ├── step_3_3_close_checkpoint.py
│   ├── step_4_1_ingest_raw_csv.py
│   ├── step_4_2_filter_clean.py
│   ├── step_4_3_write_clean_csv_and_log.py
│   ├── step_4_4_assert_min_count.py
│   ├── step_5_1_read_clean_csv.py
│   ├── step_5_2_find_pareto.py
│   ├── step_5_3_apply_pareto_filter.py
│   ├── step_5_4_save_csvs.py
│   ├── step_5_5_verify_pareto.py
│   ├── step_6_1_read_data.py
│   ├── step_6_2_plot_all.py
│   ├── step_6_3_overlay_pareto.py
│   ├── step_6_4_pairgrid.py
│   ├── step_7_1_gather_provenance.py
│   ├── step_7_2_build_report.py
│   ├── step_7_3_write_markdown.py
│   ├── step_7_4_verify_report.py
│   ├── step_8_1_verify_files.py
│   ├── step_8_2_sample_smiles.py
│   ├── step_8_3_compare_predictions.py
│   └── step_8_4_success_message.py
```

URSA can use molecular science foundation models to explore promising compounds

```

ACTIVE WORKSPACE 19:32:12 [11040/27324]
mist_agent_macho-oarfish
openai/o3

Solving problem:
You have access to the following program where you can input a SMILES string
and receive the values vdet, pdet, and density:
../bin_for_demo/MIST_FOR_URSA.sh '<SMILES_STR>'

For instance:
../bin_for_demo/MIST_FOR_URSA.sh 'CN1C=NC2=C1C(=O)N(C(=O)N2)C'
vdet: 5139.240234375
pdet: 9.848932266235352
density: 1.4493311643600464

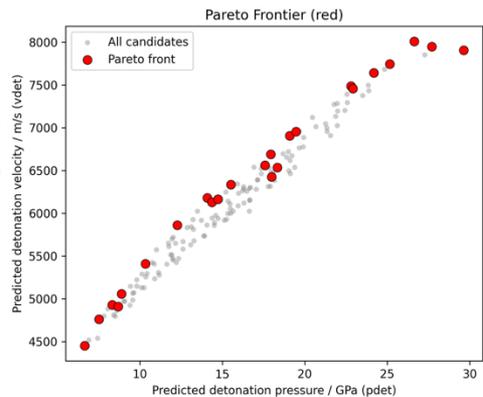
--[ BEGIN: TASK ] --
* Use your vast knowledge of chemistry to generate new energetic materials
in SMILES.
* For each SMILES string, use the model explained above to get vdet, pdet,
and density. Save results in CSV for later analysis / input to later
steps.
* You must try at least 100 different, valid, SMILES strings.
* Identify the Pareto-optimal set of SMILES that **maximize vdet and pdet**
while **minimizing density**.
* Generate plots to demonstrate this exploration.
--[ END: TASK ] --

You *MUST* use the above program, do not 'make up' values for these
compounds.
Your file names must be of the format of STEP_SUBSTEP_PURPOSE.py such as
step_1_4_read_data.py.

When appropriate, save results to CSV files from one step and read it in
for a later step rather than repeatedly running the model predictor
explained
above or hard coding result values into the Python code.

```

smiles	vdet	pdet	density
C(C#N)C(NHNO2)C(CF3)C(C(NF2)F)	4929.97949	8.323652	1.321173
C(C(N3)N3)C(NF2)C(C=CNO2)C(C#C)	4759.99951	7.528796	1.26886
C(C(N3)N3)C(NO2)C(N(=O)(=O)F)C(C(F)(F)F)	5057.8794	8.88664	1.355764
C(N3)C(CF3)C(C=CNO2)C(CF3)	4450.84375	6.662179	1.237691
C(N3)C(ONO2)C(CF3)C(N3)	5861.02051	12.276969	1.383465
C(NHNO2)C(N(=O)(=O)Cl)C(N3)C(C#C)	5410.93945	10.339898	1.375481
C1=NC(C(N3)N3)=NN1	6690.05957	17.929964	1.594969
C1=NC(C(NO2)N)=NN1	6906.39648	19.081486	1.598827
C1=NC(NF2)=NN1	6956.75684	19.470047	1.602001
C1=NC(NHNO2)=NN1	7487.31543	22.809471	1.617306
C1=NC(NO2)=NN1	7459.82959	22.92239	1.649532
C1=NC(ONO2)=NN1	7642.86816	24.188114	1.662592
C1=NN(C#C)N=N1	6181.41699	14.089297	1.395088
C1=NN(NF2)N=N1	7746.33984	25.144131	1.683435
C1=NOC(C#N)=N1			
C1=NOC(C(NF2)F)=N1			
C1=NOC(C=CNO2)=N1			
C1=NOC(CF3)=N1			
C1=NOC(OONO)=N1			
c1c(C#N)c(ONO2)c(N(=O)=O)c(C(N3)N3)c1N=NNH			
c1c(C(NF2)F)c(C#N)c(C(NO2)N)c(C#C)c1			
c1c(C(NF2)F)c(CF3)c(NF2)c(C(F)(F)F)c1N=NNHNO			
c1c(C(NF2)F)c(NHNO2)c(C(NO2)N)c(C(NO2)N)o1			
c1c(N3)c(NHNO2)c(NHNO2)c(CF3)c1N=NNO2			



Available now: <https://github.com/lanl/ursa>

URSA - The Universal Research and Scientific Agent

The flexible agentic workflow for accelerating scientific tasks. Composes information flow between agents for planning, code writing and execution, and online research to solve complex problems.

Installation

With pip:

```
git clone https://github.com/lanl/ursa.git
cd ursa
pip install -e .
```

With uv:

```
uv add <ADD PROPER ADDRESS HERE>
```

How to use this code

Better documentation will be incoming, but for now there are examples in the examples folder that should give a decent idea for how to set up some basic problems. They also should give some idea of how to pass results from one agent to another. I will look to add things with multi-agent graphs, etc. in the future.

Documentation for each URSA agent:

- [Planning Agent](#)
- [Execution Agent](#)
- [ArXiv Agent](#)
- [Web Search Agent](#)
- [Hypothesizer Agent](#)

Documentation for combining agents:

- [ArXiv -> Execution for Materials](#)
- [ArXiv -> Execution for Neutron Star Properties](#)

Sandboxing

Industry partnerships have provided access to tools and accelerated progress.



Training and support for model building.



OpenAI and Los Alamos National Laboratory announce bioscience research partnership

OpenAI and Los Alamos National Laboratory are developing evaluations to understand how multimodal AI models can be used safely by scientists in laboratory settings.

Strawberry Evaluation Results

Project	Novelty	Productivity	Solution	Strength	Importance
Subcritical limit calculations	3	4	4	3	5
High entropy alloy design	2	2	3	2	4
CPU to GPU translation		5	4	4	5
Phasor measurement unit placement	4	5	4	4	4
Adaptive control for dynamic systems	3	4	2	2	4
Quantum algorithms for fracture	3	4	4	4	4
Novel protein design	3	5	3	4	5
ICF Target Design	2	4	2	3	4
Bayesian optimization properties		4	3	3	4
Geodesic embedding in color space	3	4	3	4	5
System reliability modeling	4	5	4	3	4
Combustion science	3	2	3	3	5
Sparse sensing	2	3	2	3	3
Cybersecurity	3	5	4	4	5
Expected value proof	3	4	5	4	5
Endogenous models	3	4	3	4	5

Early access for test and evaluation.

We have the only on-prem installation of an OpenAI model anywhere in the world.

Lab partners with OpenAI to advance national security

OpenAI's latest reasoning models will be used on Venado supercomputer

Los Alamos National Laboratory has entered a partnership with OpenAI to install its latest o-series models — capable of expert reasoning for a broad span of complex scientific problems — on the Lab's [Venado](#) supercomputer, which uses NVIDIA GH200 Grace Hopper Superchips, to conduct national security research.

"As threats to the nation become more complex and more pressing, we need new approaches and advanced technologies to preserve America's security," said Laboratory Director **Thom Mason**. "Artificial intelligence models from OpenAI will allow us to do this more successfully, while also advancing our scientific missions to solve some of the nation's most important challenges."

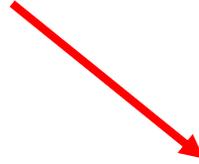
The Venado machine will be moved to a secure, classified network where it will be a shared resource for researchers from Los Alamos, Lawrence Livermore, and Sandia national labs.



TODAY'S TOP NEWS

Utility vs. Spectacle

We don't need **THIS**,
for **THIS** to be useful



5 AI Myths (and Reality) at LANL

MYTH	REALITY
✗ AI replaces mod/sim	✓ AI accelerates mod/sim — physics stays truth
✗ GenAI is too wild for science	✓ GenAI is a controlled interface (read/write/code)
✗ We need AGI	✓ Narrow models deliver mission value now
✗ Agents are for booking trips	✓ Agents automate workflows (data → run → report)
✗ We hand decisions to AI	✓ AI advises; humans decide (bounded autonomy)

AI is a force multiplier—not a replacement.

LANL's ArtIMis in Summary . . .

- Leverage frontier industry reasoning models
- AI ecosystem of reasoning agents powering non-language science foundation models
- Partnerships with industry and academia
- Dozens of papers – CS as well as in applied domains
- Deep application to LANL mission
- Feeding directly into Genesis Mission project

URSA



<https://github.com/lanl/ursa>

Thanks for the Invite!

Feel free to reach out

Nathan DeBardeleben, Ph.D.

High Performance Computing Design (HPC-DES)

ndebard@lanl.gov